

Schwartz
11.6 (a)

We wish to show $\bar{\psi}_L \gamma_\mu \psi_R = \bar{\psi}_R \gamma_\mu \psi_L = 0$

We are working with Left and Right handed spinors, so we are implicitly working in the Dirac basis, Weyl Rep.

$$\text{Then } \bar{\psi}_L \gamma_\mu \psi_R = \overline{\left[\frac{1}{2}(1-\gamma^5)\psi \right]} \gamma_\mu \left[\frac{1}{2}(1+\gamma^5)\psi \right]$$

$$= \frac{1}{4} \left[(1-\gamma^5)\psi \right]^\dagger \gamma_0 \gamma_\mu (1+\gamma^5)\psi$$

$$= \frac{1}{4} \psi^\dagger \underbrace{(1-\gamma^5)^T \gamma_0 \gamma_\mu (1+\gamma^5)}_1 \psi$$

$$(1-\gamma^5)^T \gamma_0 \gamma_\mu (1+\gamma^5)$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & \\ & -1 \end{pmatrix} \begin{pmatrix} \sigma & \\ & \sigma \end{pmatrix} \begin{pmatrix} 0 & \\ & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & \\ & \sigma \end{pmatrix} = \boxed{0}$$

$$\text{Similarly, } \bar{\psi}_R \gamma_\mu \psi_L = \frac{1}{4} \psi^\dagger \underbrace{(1+\gamma^5)^T \gamma_0 \gamma_\mu (1-\gamma^5)}_1 \psi$$

$$(1+\gamma^5)^T \gamma_0 \gamma_\mu (1-\gamma^5) = \begin{pmatrix} 0 & 1 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & \\ & -1 \end{pmatrix} \begin{pmatrix} \sigma & \\ & \sigma \end{pmatrix} \begin{pmatrix} 1 & \\ & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \sigma & \\ & \sigma \end{pmatrix}$$

$$= \boxed{0}$$

(b) In rest frame, we can write

$$u_{\uparrow} = \begin{pmatrix} \vec{\xi}_{\uparrow} \\ \xi_{\uparrow} \end{pmatrix}, \quad u_{\downarrow} = \begin{pmatrix} \vec{\xi}_{\downarrow} \\ \xi_{\downarrow} \end{pmatrix}, \quad \text{where } \vec{\xi}_{\uparrow} \cdot \vec{\xi}_{\downarrow} = 0, \\ \vec{\xi}_{\uparrow}, \vec{\xi}_{\downarrow} \text{ are 2D vector objects}$$

$$\begin{aligned} \bar{u}_{\uparrow} \gamma_{\mu} u_{\downarrow} &= \begin{pmatrix} \vec{\xi}_{\uparrow}^* & \xi_{\uparrow}^* \end{pmatrix} \gamma_0 \gamma_{\mu} \begin{pmatrix} \vec{\xi}_{\downarrow} \\ \xi_{\downarrow} \end{pmatrix} \\ &= \begin{pmatrix} \vec{\xi}_{\uparrow}^* & \xi_{\uparrow}^* \end{pmatrix} \begin{pmatrix} \mathbb{1} \\ \mathbb{0} \end{pmatrix} \begin{pmatrix} \sigma_{\mu} \\ \bar{\sigma}_{\mu} \end{pmatrix} \begin{pmatrix} \vec{\xi}_{\downarrow} \\ \xi_{\downarrow} \end{pmatrix} \\ &= \vec{\xi}_{\uparrow}^* \bar{\sigma}_{\mu} \vec{\xi}_{\downarrow} + \xi_{\uparrow}^* \sigma_{\mu} \xi_{\downarrow} \end{aligned}$$

Recall $\sigma_{\mu} = (\mathbb{1}, \vec{\sigma})$, $\bar{\sigma}_{\mu} = (\mathbb{1}, -\vec{\sigma})$, so all 3-space components vanish, but by orthogonality of $\vec{\xi}_{\uparrow}, \vec{\xi}_{\downarrow}$, the 0-th component vanishes as well.

Now for v , In rest frame,

$$v_{\uparrow} = \begin{pmatrix} \eta_{\uparrow} \\ -\eta_{\uparrow} \end{pmatrix}, \quad v_{\downarrow} = \begin{pmatrix} \eta_{\downarrow} \\ -\eta_{\downarrow} \end{pmatrix}, \quad \eta_{\uparrow}, \eta_{\downarrow} \text{ 2D objects, } \cancel{\text{2D vector}}$$
$$\eta_{\uparrow} \eta_{\downarrow} = 0$$

$$\bar{v}_{\uparrow} \gamma_{\mu} v_{\downarrow} = (\eta_{\uparrow}^* \quad -\eta_{\uparrow}^*) \begin{pmatrix} \mathbb{1} & \\ & \mathbb{1} \end{pmatrix} \begin{pmatrix} \sigma_{\mu} \\ \bar{\sigma}_{\mu} \end{pmatrix} \begin{pmatrix} \eta_{\downarrow} \\ -\eta_{\downarrow} \end{pmatrix}$$

$$= (-\eta_{\uparrow}^* \quad \eta_{\uparrow}^*) \begin{pmatrix} -\sigma_{\mu} \eta_{\downarrow} \\ \bar{\sigma}_{\mu} \eta_{\downarrow} \end{pmatrix}$$

$$= \eta_{\uparrow}^* \sigma_{\mu} \eta_{\downarrow} + \eta_{\uparrow}^* \bar{\sigma}_{\mu} \eta_{\downarrow}$$

By same reasoning as for u , this vanishes.